

# Signals & Systems

## HW

### Problem Set 1 (Due Wednesday 1/27)

Problems A1.1, A1.2, 1.52, 1.53, 1.54

#### Problem A1.1

Determine whether or not each of the following continuous-time signals is periodic. If the signal is periodic, determine its fundamental period.

(a)  $x(t) = 3 \cos(\sqrt{2}t + \frac{\pi}{4})$

(b)  $x(t) = e^{j(2t-1)}$

(c)  $x(t) = [\cos(4t - \frac{\pi}{3})]^2$

(d)  $x(t) = \mathcal{O}d\{\cos(4\pi t)u(t)\}$

(e)  $x(t) = \mathcal{O}d\{\sin(4\pi t)u(t)\}$

(f)  $x(t) = \sum_{n=-\infty}^{\infty} e^{-(3t-n)}u(3t-n)$

(g)  $x(t) = \cos(4t) + \sin(4\pi t)$ .

#### Problem A1.2

Determine whether or not each of the following discrete-time signals is periodic. If the signal is periodic, determine its fundamental period.

(a)  $x[n] = \sin(\frac{3}{7}\pi n - 1)$

(b)  $x[n] = \cos(\pi \frac{n}{8} - \pi)$

(c)  $x[n] = \cos(\frac{\pi}{6}n^2)$

(d)  $x[n] = \cos(\frac{\pi}{3}n) \cos(\frac{\pi}{6}n)$

(e)  $x[n] = 2 \cos(\frac{\pi}{4}n) + \sin(\frac{\pi}{3}n) - 4 \cos(\frac{1}{2}n + \frac{\pi}{6})$

### Problem Set 2 (Due Monday 2/1)

Problems 1.21, 1.22, 1.32, 1.36

### Problem Set 3 (Due Monday 2/8)

Problems A1.3, A1.4, 1.31, A1.5

**Problem A1.3**

Consider the following properties

1. Memoryless
2. Time-invariant
3. Linear
4. Causal
5. Stable

Determine which of these properties hold and which do not hold for each of the following continuous-time systems. Justify your answers. In each example,  $y(t)$  denotes the system output and  $x(t)$  is the system input.

(a)  $y(t) = x(t - 3) + x(3 - t)$

(b)  $y(t) = \cos(-3t)x(t)$

(c)  $y(t) = \int_{-\infty}^t x(\tau)d\tau$

(d)  $y(t) = \begin{cases} 0 & t < 0 \\ x(t) + x(2 - t) & t \geq 0 \end{cases}$

(e)  $y(t) = \begin{cases} 0 & x(t + 2) < 0 \\ x(t) + x(2 - t) & x(t + 2) \geq 0 \end{cases}$

(f)  $y(t) = x(2t)$ .

(g)  $y(t) = \frac{dx(t-1)}{dt}$

**Problem A1.4**

Consider the following properties

1. Memoryless
2. Time-invariant
3. Linear
4. Causal
5. Stable

Determine which of these properties hold and which do not hold for each of the following discrete-time systems. Justify your answers. In each example,  $y[n]$  denotes the system output and  $x[n]$  is the system input.

(a)  $y[n] = x[1 - n]$

(b)  $y[n] = x[2n - 2] - 2x[n - 8]$

(c)  $y[n] = \sin(\pi n)x[n]$

(d)  $y[n] = \mathcal{E}v\{x[n + 1]\}$

$$(e) y[n] = \begin{cases} x[n-1] & n \geq 1 \\ 0 & n = 0 \\ x[n] & n \leq -1 \end{cases}$$

$$(f) y[n] = \begin{cases} x[n] & n \geq 1 \\ 0 & n = 0 \\ x[n] & n \leq -1 \end{cases}$$

$$(g) y[n] = x[-4n + 1]$$

**Problem A1.5**

Determine if the following systems are

- (a) time-invariant
- (b) stable
- (c) causal
- (d) linear.

**Justify your answer**

1. A system with input  $x(t)$  giving output

$$y(t) = \int_{t-10}^t \cos(\tau)x(\tau)d\tau$$

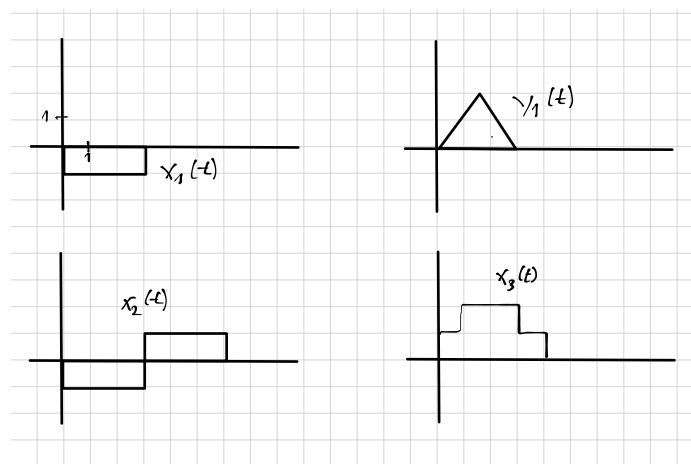
2. A system with input  $x[n]$  giving output

$$y[n] = n^2x[n^2]$$

**Problem Set 4 (Due Wednesday 2/17)**

Problems 1.29, A1.6, A2.1, 2.24

**Problem A1.6**



When the input to a linear time-invariant system is given by  $x_1(t)$ , the output is  $y_1(t)$ , see the figure.

- (a) If the input is  $x_2(t)$  (see the figure), what is the output?
- (b) If the input is  $x_3(t)$  (see the figure), what is the output?

**Problem A2.1**

Compute the convolution  $y[n] = x[n] * h[n]$  of the following pair of signals

(a)  $x[n] = \alpha^n u[n-1]$ ,  $h[n] = \beta^n u[n]$ ,  $\alpha \neq \beta$ .

(b)  $x[n] = \alpha^n u[n-1]$ ,  $h[n] = \alpha^n u[n]$

(c)  $x[n] = \left(\frac{1}{2}\right)^n u[n-3]$ ,  $h[n] = (-3)^n u[4-n]$ .

(d)  $x[n] = \begin{cases} 1 & 0 \leq n \leq 5 \\ 0 & \text{otherwise} \end{cases}$ ,  $h[n] = \begin{cases} 1 & 1 \leq n \leq 5 \\ 1 & 8 \leq n \leq 13 \\ 0 & \text{otherwise} \end{cases}$

**Problem Set 5 (Due Monday 2/22)**

Problems 2.22, A2.3, A2.4, A2.5

**Problem A2.3**

The following are the impulse responses of discrete-time LTI systems. Determine whether each system is causal and/or stable. Justify your answers. The justification for stability needs to in terms of the summation condition.

(a)  $h[n] = \left(\frac{1}{2}\right)^n u[n]$

(b)  $h[n] = (-1.8)^n u[n-2]$

(c)  $h[n] = (2)^n u[-n+1]$

(d)  $h[n] = \left(\frac{6}{5}\right)^n u[-1-n]$

(e)  $h[n] = \left(-\frac{1}{8}\right)^n u[n] + 1.01^{n+1} u[n+1]$

(f)  $h[n] = \left(-\frac{1}{8}\right)^n u[n] + 0.99^n u[1-n]$

(g)  $h[n] = n^2 \left(\frac{1}{2}\right)^n u[n-3]$

**Problem A2.4**

The following are the impulse responses of continuous-time LTI systems. Determine whether each system is causal and/or stable. Justify your answers. The justification for stability needs to in terms of the integration condition.

(a)  $h(t) = e^{-4t} u(-t-2)$

(b)  $h(t) = e^{-\frac{1}{2}t} u(t-2)$

(c)  $h(t) = e^{-1.1t} u(t+100)$

(d)  $h(t) = e^{-4t} u(t-2)$

(e)  $h(t) = e^{-|t|}$

(f)  $h(t) = t^2 e^{-t/2} u(t)$

(g)  $h(t) = (2e^{-t/2} - e^{(10-t)/10}) u(t+2)$

(h)  $h(t) = \frac{t}{t^2+1}$

**Problem A2.5**

1. The impulse response of an LTI system is given by

$$h(t) = \cos(t)u(t)$$

If the input is  $x(t) = u(t)$ , calculate the output.

2. The impulse response of an LTI system is given by

$$h[n] = (-2)^{|n|}$$

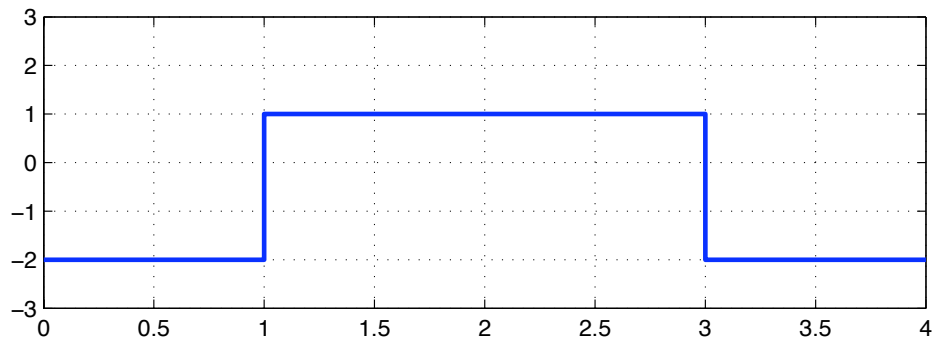
If the input is  $x[n] = u[n] - u[n - 2]$ , calculate the output.

**Problem Set 6 (Due Monday 3/7)**

Problems 2.30, 3.22, 3.23, 3.24, 3.26, A3.5

**Problem A3.5**

The following plot shows a signal  $x(t)$  with period  $T = 4$ .



1. Find the Fourier coefficients of  $x(t)$ .
2. *Sketch* the the signal with period  $T = 4$  having Fourier coefficients

$$a_k = \begin{cases} 0 & k = 0 \\ -3 \frac{\sin(k\frac{\pi}{2})}{k\pi} & k \neq 0 \end{cases}$$

3. *Sketch* the signal with period  $T = 4$  having Fourier coefficients

$$a_k = \begin{cases} -\frac{1}{2} & k = 0 \\ -6e^{j\frac{\pi}{4}k} \frac{\sin(k\frac{\pi}{2})}{k\pi} & k \neq 0 \end{cases}$$

4. *Sketch* the signal with period  $T = 4$  having Fourier coefficients

$$a_k = \begin{cases} -\frac{1}{2} & k = 0 \\ 3j \frac{\sin(k\frac{\pi}{2})}{k^2\pi} & k \neq 0 \end{cases}$$